EUROPEAN SOUTHERN OBSERVATORY



Organisation Européenne pour des Recherches Astronomiques dans l'Hémisphère Austral Europäische Organisation für astronomische Forschung in der südlichen Hemisphäre

VERY LARGE TELESCOPE

Reflex FLAMES-UVES Tutorial

VLT-MAN-ESO-19500-XXXX

Issue 1.10

Date 2018-04-01

L

Γ

٦

Prepared:	Andrea Modigliani	2018-04-01	
	Name	Date	Signature
Approved:	W.Freudling		
	Name	Date	Signature
Released:	M. Sterzik		
	Name	Date	Signature

This page was intentionally left blank

Change record

Issue/Rev.	Date	Section/Parag. affected	Reason/Initiation/Documents/Remarks
1.0	15/11/2013	All	First public release
1.10	01/04/2018	All	Update to Reflex 2.9

This page was intentionally left blank

Doc:	VLT-MAN-ESO-19500-XXXX
Issue:	Issue 1.10
Date:	Date 2018-04-01
Page:	5 of 30

Contents

1	Intro	oductio	n And Scope	7
2	Soft	ware In	stallation	8
	2.1	Installi	ing Reflex workflows via macports	8
	2.2	Installi	ing Reflex workflows via rpm/yum	8
	2.3	Installi	ing Reflex workflows via install_esoreflex	9
3	Dem	io Data		11
4	Quio	ck Start	: Reducing The Demo Data	12
5	Abo	ut The I	Reflex Canvas	16
	5.1	Saving	g And Loading Workflows	16
	5.2	Button	IS	16
	5.3	Workfl	ow States	16
6	The	uves W	orkflow	17
	6.1	Workfl	low Canvas Parameters	17
	6.2	Workfl	low Actors	18
		6.2.1	Simple Actors	18
		6.2.2	Composite Actors	18
		6.2.3	Recipe Execution within Composite Actors	19
		6.2.4	Lazy Mode	21
	6.3	Workfl	low Steps	22
		6.3.1	Step 1: Data Organisation And Selection	22
		6.3.2	Step 2: Recipe execution	25
		6.3.3	Step 3: Final products	25
7	Trou	ıblesho	oting	26
8	Freq	quently	Asked Questions	27

		Doc:	VLT-MAN-ESO-19500-XXXX
ESO	Reflex FLAMES-UVES Tutorial	Issue:	Issue 1.10
LOU	Kenex I Er hvileb e veb Tutoriur	Date:	Date 2018-04-01
		Page:	6 of 30

Doc:	VLT-MAN-ESO-19500-XXXX
Issue:	Issue 1.10
Date:	Date 2018-04-01
Page:	7 of 30

1 Introduction And Scope

Reflex is the ESO Recipe Flexible Execution Workbench, an environment to run ESO VLT pipelines which employs a workflow engine to provide a real-time visual representation of a data reduction cascade, called a workflow, which can be easily understood by most astronomers. The basic philosophy and concepts of Reflex have been discussed by Freudling et al. (2013A&A...559A..96F). Please reference this article if you use Reflex in a scientific publication.

Reflex and the data reduction workflows have been developed by ESO and instrument consortia and they are fully supported. If you have any issue, please contact *usd-help@eso.org* for further support.

This document is a tutorial designed to enable the user to employ the uves workflow to reduce his/her data in a user-friendly way, concentrating on high-level issues such as data reduction quality and signal-to-noise (S/N) optimisation.

A workflow accepts science and calibration data, as downloaded from the archive using the CalSelector tool¹ (with associated raw calibrations) and organises them into DataSets, where each DataSet contains one science object observation (possibly consisting of several science files) and all associated raw and static calibrations required for a successful data reduction. The data organisation process is fully automatic, which is a major time-saving feature provided by the software. The DataSets selected by the user for reduction are fed to the workflow which executes the relevant pipeline recipes (or stages) in the correct order. Full control of the various recipe parameters is available within the workflow, and the workflow deals automatically with optional recipe inputs via built-in conditional branches. Additionally, the workflow stores the reduced final data products in a logically organised directory structure employing user-configurable file names.

This tutorial deals with the reduction of FLAMES-UVES observations only via the FLAMES-UVES workflow. The user is referred to the FLAMES-UVES web page (http://www.eso.org/sci/facilities/paranal/instruments/flames/) for more information on the instrument itself, and the FLAMES-UVES pipeline user manual for the details of the pipeline recipes (http://www.eso.org/sci/software/pipelines/).

The workflow uses association rules known to work with files downloaded from the ESO archive with the CalSelector tool (from year 2003 onwards). For datasets where the data were directly delivered to the PI (e.g. in DVDs) see 7.

¹http://www.eso.org/sci/archive/calselectorInfo.html

Doc:	VLT-MAN-ESO-19500-XXXX
Issue:	Issue 1.10
Date:	Date 2018-04-01
Page:	8 of 30

2 Software Installation

Reflex and the workflows can be installed in different ways: via package repositories, via the install_esoreflex script or manually installing the software tar files.

The recommended way is to use the package repositories if your operating system is supported. The macports repositories support OS X, while the rpm/yum repositories support Fedora 20 to 25. For any other operating system it is recommended to use the install_esoreflex script.

2.1 Installing Reflex workflows via macports

This method is supported for the OS X operating system. It is assumed that macports (*http://www.macports.org*) and java are installed. If you have any problem with this installation method, please read the full documentation at

http://www.eso.org/sci/software/pipelines/installation/macports.html.

For a quick installation, the following steps will install the ESO pipeline macports repository, the uves pipeline, including the Reflex workflow support and Reflex itself:

• Set up the repository:

```
# curl ftp://ftp.eso.org/pub/dfs/pipelines/repositories/macports/setup/Portfile -o Portfile
# sudo port install
# sudo port sync
```

- Install the uves pipeline:
 - # sudo port install esopipe-uves-all

2.2 Installing Reflex workflows via rpm/yum

This method is supported for Fedora 20/21/22/23/24/25 operating systems. If you have any problem with this installation method, please read the full documentation at *http://www.eso.org/sci/software/pipelines/installation/rpm.html*.

For a quick installation, the following steps will install the ESO pipeline rpm repository, the uves pipeline, including the Reflex workflow support and Reflex itself:

• Set up the repository for Fedora 20/21:

```
# sudo yum install yum-utils
# sudo yum-config-manager \
    --add-repo=ftp://ftp.eso.org/pub/dfs/pipelines/repositories/fedora/esorepo.repo
```

• Set up the repository for Fedora 22/23/24/25:

```
# sudo dnf install dnf-plugins-core
# sudo dnf config-manager \
    --add-repo=ftp://ftp.eso.org/pub/dfs/pipelines/repositories/fedora/esorepo.repo
```

- Install the uves pipeline (Fedora 20/21): # sudo yum install esopipe-uves-all
- Install the uves pipeline (Fedora 22/23/24/25): # sudo dnf install esopipe-uves-all

2.3 Installing Reflex workflows via install_esoreflex

The software pre-requisites for Reflex 2.9 may be found at: *http://www.eso.org/sci/software/pipelines/reflex_workflows*

To install the Reflex 2.9 software and demo data, please follow these instructions:

1. From any directory, download the installation script:

wget ftp://ftp.eso.org/pub/dfs/reflex/install_esoreflex

2. Make the installation script executable:

chmod u+x install_esoreflex

3. Execute the installation script:

./install_esoreflex

and the script will ask you to specify three directories: the download directory <download_dir>, the software installation directory <install_dir>, and the directory to be used to store the demo data <data_dir>. If you do not specify these directories, then the installation script will create them in the current directory with default names.

- 4. You will be asked whether you want to use your Internet connection. Unless you want to reuse already downloaded packages (only advanced users), use the default Yes.
- 5. You will be given a choice of pipelines (with the corresponding workflows) to install. Please specify the numbers for the pipelines you require, separated by a space, or type "A" for all pipelines.
- 6. For the pipelines to be installed you will be prompted for the demo data sets to be installed. Type "A" for all demo datasets. Take into account that if you are installing in a directory that already contains data, it won't be removed.
- 7. The script will also detect whether previous versions of the workflows or Reflex were installed and in this case you have the option to update links or remove obsolete cache directories. It is advised to use the defaults.
- 8. If some of the prerequisite binaries for Reflex are not under one of the paths indicated by the command,

		Doc:	VLT-MAN-ESO-19500-XXXX
ESO	Reflex FLAMES-UVES Tutorial	Issue:	Issue 1.10
LOU		Date:	Date 2018-04-01
		Page:	10 of 30

getconf PATH

then you will need to add the appropriate paths as a colon separated list to the esoreflex.path parameter in the configuration file <install_dir>/etc/esoreflex.rc. This will usually be necessary when the FITS viewer (fv) is installed outside of /usr/bin. As an example, assume fv is installed into the directory /usr/local/fv5.4, the file esoreflex.rc should then have the line setting esoreflex.path look similar to the following:

esoreflex.path=/usr/local/fv5.4

In the case of OS X /Applications/fv.app/Contents/MacOS/ is the typically installation directory. Thus, this should be similar to the following line instead:

esoreflex.path=/opt/local/bin:/Applications/fv.app/Contents/MacOS

9. To start Reflex, issue the command:

```
<install_dir>/bin/esoreflex
```

It may also be desirable to set up an alias command for starting the Reflex software, using the shell command alias. Alternatively, the PATH variable can be updated to contain the <install_dir>/bin directory.

Doc:	VLT-MAN-ESO-19500-XXXX
Issue:	Issue 1.10
Date:	Date 2018-04-01
Page:	11 of 30

3 Demo Data

Together with the pipeline you will also receive a demo data set, that allows you to run the Reflex FALES-UVES workflow without any changes in parameters. This way you have a data set to experiment with before you start to work on your own data. The demo data for FLAMES-UVES includes example data for the workflow.

Note that you will need a minimum of $\sim 3.9 \text{ GB}$, $\sim 0.6 \text{ GB}$ and $\sim 6.8 \text{ GB}$ of free disk space for the directories <download_dir>, <install_dir> and <data_dir>, respectively. The FLAMES-UVES demo data have been retrieved with the CalSelector tool².

²http://www.eso.org/sci/archive/calselectorInfo.html

Doc:	VLT-MAN-ESO-19500-XXXX
Issue:	Issue 1.10
Date:	Date 2018-04-01
Page:	12 of 30

4 Quick Start: Reducing The Demo Data

For the user who is keen on starting reductions without being distracted by detailed documentation, we describe the steps to be performed to reduce the science data provided in the user demo data set supplied with the Reflex 2.9 release. By following these steps, the user should have enough information to perform a reduction of his/her own data without any further reading:

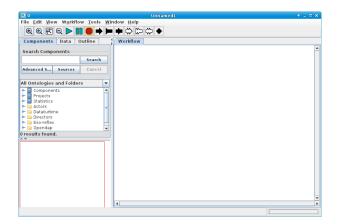


Figure 4.1: The empty Reflex canvas.

1. Start the Reflex application:

esoreflex &

If install_esoreflex was used or manual installation was performed then the start command is:

<install_dir>/bin/esoreflex &

The empty Reflex canvas as shown in Figure 4.1 will appear.

- 2. Now open the uves workflow by clicking on File -> Open File, selecting first uves-5.9.0 and then the file uves.xml in the file browser. You will be presented with the workflow canvas shown in Figure 4.2. Note that the workflow will appear as a canvas in a new window.
- 3. To aid in the visual tracking of the reduction cascade, it is advisable to use component (or actor) highlighting. Click on Tools -> Animate at Runtime, enter the number of milliseconds representing the animation interval (100 ms is recommended), and click OK.
- 4. Under "Setup Directories" in the workflow canvas there are seven parameters that specify important directories (green dots). Changing the value of ROOT_DATA_DIR and/or RAW_DATA_DIR is the only

necessary modification if you want to process data other than the demo data³, since the value of this parameter specifies the working directory within which the other directories are organised. Double-click on the parameter ROOT_DATA_DIR and a pop-up window will appear allowing you to modify the directory string, which you may either edit directly, or use the Browse button to select the directory from a file browser. When you have finished, click OK to save your changes.

- 5. Click the \triangleright button to start the workflow
- 6. The workflow will highlight the Data Organiser actor which recursively scans the raw data directory (specified by the parameter RAW_DATA_DIR under "Setup Directories" in the workflow canvas) and constructs the DataSets. Note that the raw and static calibration data must be present either in RAW_DATA_DIR or in CALIB_DATA_DIR, otherwise DataSets may be incomplete and cannot be processed. However, if the same reference file was downloaded twice to different places this creates a problem as Reflex cannot decide which one to use.
- 7. The Data Set Chooser actor will be highlighted next and will display a "Select Datasets" window (see Figure 4.3) that lists the DataSets along with the values of a selection of useful header keywords⁴. The first column consists of a set of tick boxes which allow the user to select the DataSets to be processed. By default all complete DataSets which have not yet been reduced will be selected.
- 8. Click the Continue button and watch the progress of the workflow by following the red highlighting of the actors. A window will show which DataSet is currently being processed.
- 9. Once the reduction of all DataSets has finished, a pop-up window called *Product Explorer* will appear, showing the datasets which have been reduced together with the list of final products. This actor allows the user to inspect the final data products, as well as to search and inspect the input data used to create any of the products of the workflow. Figure 4.4 shows the Product Explorer window.
- 10. After the workflow has finished, all the products from all the DataSets can be found in a directory under END_PRODUCTS_DIR with the named with the workflow start timestamp. Further subdirectories will be found with the name of each DataSet.

Well done! You have successfully completed the quick start section and you should be able to use this knowledge to reduce your own data. However, there are many interesting features of Reflex and the uses workflow that merit a look at the rest of this tutorial.

³If you used the install script install_esoreflex, then the value of the parameter ROOT_DATA_DIR will already be set correctly to the directory where the demo data was downloaded.

⁴The keywords listed can be changed by right-clicking on the DataOrganiser Actor, selecting Configure Actor, and then changing the list of keywords in the second line of the pop-up window.

Doc:	VLT-MAN-ESO-19500-XXXX
Issue:	Issue 1.10
Date:	Date 2018-04-01
Page:	14 of 30

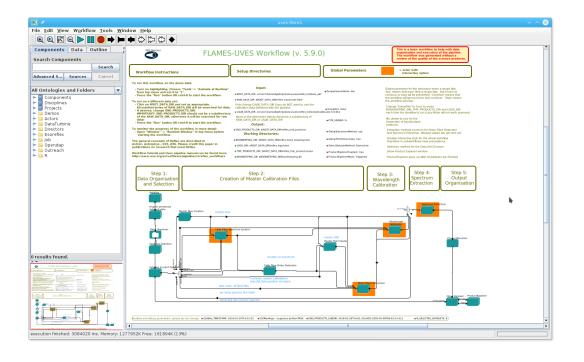


Figure 4.2: FLAMES-UVES workflow general layout.

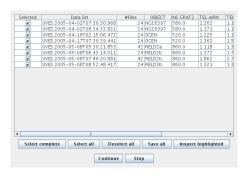


Figure 4.3: The "Select Datasets" pop-up window.

		Doc:	VLT-MAN-ESO-19500-XXXX
ESO	Reflex FLAMES-UVES Tutorial	Issue:	Issue 1.10
		Date:	Date 2018-04-01
		Page:	15 of 30

Search products	Provenance Tree	Category
□ Last Hour 💌		MWXB_SCI_REDU
	UVES.2005-04-02T07:30:30.968.fits F	
		FIB_LINE_TABLE_
From 12/11/13 10:31:17		MASTER_BIAS_RE
To 12/11/13 10:32:33 9		FIB_FF_NOR_RED
		FIB_ORDEF_TABL
Search		SLIT_FF_COM_REI
		FIB_FF_SGC_RED
Dataset		MASTER_BIAS_RE
-04-02T07:30:30.968		FIB_FF_COM_RED
5397_UVES-SGB_MEDUSA_MWXB_SCI_REDU_4.fits		SLIT_FF_NOR_REI
6397_UVES-SGB_MEDUSA_MWXB_SCI_REDL_5.fits		FIB_FF_BPC_REDI
5397_UVES-SGB_MEDUSA_MWXB_SCI_REDU.fits		SLIT_FF_BNC_REC
6397_UVES-SGB_MEDUSA_ERR_MWXB_SCI_REDL_6.fits		SLIT_FF_SGC_REC
6397_UVES-SGB_MEDUSA_MWXB_SCI_REDL_2.fits		SLIT_FF_BNC_REC
6397_UVES-SGB_MEDUSA_MWXB_SCI_REDL_4.fits		SLIT_FF_DTC_REC
6397_UVES-SGB_MEDUSA_ERR_MWXB_SCI_REDU_2.fits		SLIT_FF_DTC_REC
6397_UVES-SGB_MEDUSA_ERR_MWXB_SCI_REDL_7.fits		FIB_FF_NSG_RED
6397_UVES-SGB_MEDUSA_ERR_MWXB_SCI_REDU.fits		FIB_FF_NSG_RED
6397_UVES-SGB_MEDUSA_MWXB_SCI_REDU_7.fits		FIB_FF_BPC_RED
6397_UVES-SGB_MEDUSA_MWXB_SCI_REDL_7.fits		FIB_ORDEF_TABL
6397_UVES-SGB_MEDUSA_ERR_MWXB_SCI_REDU_6.fits		SLIT_FF_BPC_REC
6397_UVES-SGB_MEDUSA_ERR_MWXB_SCI_REDL_3.fits		FIB_FF_DTC_REDI
6397_UVES-SGB_MEDUSA_MWXB_SCI_REDL.fits		FIB_FF_COM_RED
6397_UVES-SGB_MEDUSA_ERR_MWXB_SCI_REDU_7.fits		FIB_FF_NOR_RED
	A	• • • •
		Inspect
	Continue	

Figure 4.4: The Provenance Explorer shows all datasets reduced in previous executions together with the full reduction chain for all the pipeline products.

Doc:	VLT-MAN-ESO-19500-XXXX
Issue:	Issue 1.10
Date:	Date 2018-04-01
Page:	16 of 30

5 About The Reflex Canvas

5.1 Saving And Loading Workflows

In the course of your data reductions, it is likely that you will customise the workflow for various data sets, even if this simply consists of editing the ROOT_DATA_DIR to a different value for each data set. Whenever you modify a workflow in any way, you have the option of saving the modified version to an XML file using File -> Export As (which will also open a new workflow canvas corresponding to the saved file). The saved workflow may be opened in subsequent Reflex sessions using File -> Open. Saving the workflow in the default Kepler format (.kar) is only advised if you do not plan to use the workflow with another computer.

5.2 Buttons

At the top of the Reflex canvas are a set of buttons which have the following functions:

- 🗨 Zoom in.
- 🔍 Reset the zoom to 100%.
- 🗷 Zoom the workflow to fit the current window size (Recommended).
- 🔍 Zoom out.
- Run (or resume) the workflow.
- 🛄 Pause the workflow execution.
- Stop the workflow execution.

The remainder of the buttons (not shown here) are not relevant to the workflow execution.

5.3 Workflow States

A workflow may only be in one of three states: executing, paused, or stopped. These states are indicated by the yellow highlighting of the \triangleright , \blacksquare , and \bullet buttons, respectively. A workflow is executed by clicking the button. Subsequently the workflow and any running pipeline recipe may be stopped immediately by clicking the \bullet button, or the workflow may be paused by clicking the \blacksquare button which will allow the current actor/recipe to finish execution before the workflow is actually paused. After pausing, the workflow may be resumed by clicking the \bullet button again.

Doc:	VLT-MAN-ESO-19500-XXXX
Issue:	Issue 1.10
Date:	Date 2018-04-01
Page:	17 of 30

6 The uves Workflow

The uves workflow canvas is organised into a number of areas. From top-left to top-right you will find general workflow instructions, directory parameters, and global parameters. In the middle row you will find five boxes describing the workflow general processing steps in order from left to right, and below this the workflow actors themselves are organised following the workflow general steps.

6.1 Workflow Canvas Parameters

The workflow canvas displays a number of parameters that may be set by the user. Under "Setup Directories" the user is only required to set the RAW_DATA_DIR to the working directory for the DataSet(s) to be reduced, which, by default, is set to the directory containing the demo data. The RAW_DATA_DIR is recursively scanned by the Data Organiser actor for input raw data. The directory CALIB_DATA_DIR, which is by default within the pipeline installation directory, is also scanned by the Data Organiser actor to find any static calibrations that may be missing in your DataSet(s). If required, the user may edit the directories BOOKKEEPING_DIR, LOGS_DIR, TMP_PRODUCTS_DIR, and END_PRODUCTS_DIR, which correspond to the directories where book-keeping files, logs, temporary products and end products are stored, respectively (see the Reflex User Manual for further details; Forchì (2012)).

There is a mode of the Data Organiser that skips the built-in data organisation and uses instead the data organisation provided by the CalSelector tool. To use this mode, click on Use CalSelector associations in the Data Organiser properties and make sure that the input data directory contains the XML file downloaded with the CalSelector archive request.

Under the "Global Parameters" area of the workflow canvas, the user may set the FITS_VIEWER parameter to the command used for running his/her favourite application for inspecting FITS files. Currently this is set by default to fv, but other applications, such as ds9, skycat and gaia for example, may be useful for inspecting image data. Note that it is recommended to specify the full path to the visualization application (an alias will not work).

By default the EraseDirs parameter is set to false, which means that no directories are cleaned before executing the workflow, and the recipe actors will work in Lazy Mode (see Section 6.2.4), reusing the previous pipeline recipe outputs where input files and parameters are the same as for the previous execution, which saves considerable processing time. Sometimes it is desirable to set the EraseDirs parameter to true, which forces the workflow to recursively delete the contents of the directories specified by BOOKKEEPING_DIR, LOGS_DIR, and TMP_PRODUCTS_DIR. This is useful for keeping disk space usage to a minimum and will force the workflow to fully re-reduce the data each time the workflow is run.

The parameter RecipeFailureMode controls the behaviour in case that a recipe fails. If set to Continue, the workflow will trigger the next recipes as usual, but without the output of the failing recipe, which in most of the cases will lead to further failures of other recipes without the user actually being aware of it. This mode might be useful for unattended processing of large number of datasets. If set to Ask, a pop-up window will ask whether the workflow should stop or continue. This is the default. Alternatively, the Stop mode will stop the workflow execution immediately.

The parameter GlobalPlotInteractivity controls whether the interactive windows will appear for those windows which are *enabled* by default. The possible values are true, false. Take into account that some

Doc:	VLT-MAN-ESO-19500-XXXX
Issue:	Issue 1.10
Date:	Date 2018-04-01
Page:	18 of 30

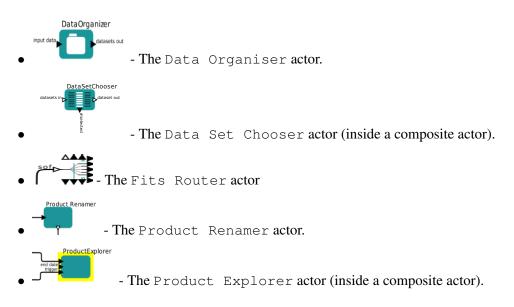
windows are disabled in the default configuration and therefore are not affected by this parameter.

The parameter ProductExplorerMode controls whether the ProductExplorer actor will show its window or not. The possible values are Enabled, Disabled and Triggered. The latter, recommended, means that the ProductExplorer actor will be shown only at the end of the workflow execution.

6.2 Workflow Actors

6.2.1 Simple Actors

Simple actors have workflow symbols that consist of a single (rather than multiple) green-blue rectangle. They may also have an icon within the rectangle to aid in their identification. The following actors are simple actors:



Access to the parameters for a simple actor is achieved by right-clicking on the actor and selecting Configure Actor. This will open an "Edit parameters" window. Note that the Product Renamer actor is a jython script (Java implementation of the Python interpreter) meant to be customised by the user (by double-clicking on it).

6.2.2 Composite Actors

Composite Actors have workflow symbols that consist of multiply-layered green-blue rectangles. They generally do not have a logo within the rectangle. A Composite Actor represents a combination of more Simple or Composite Actors which hides over-complexity from the user in the top-level workflow.

Composite Actors may also be expanded for inspection. To do this, right-click on the actor and select Open Actor, which will expand the Composite Actor components in a new Reflex canvas window. If the Composite Actor corresponds to a pipeline recipe, then the corresponding RecipeExecuter actor will be present as a Simple Actor, and its parameters are accessible as for any other Simple Actor. Alternatively you may still find Composite Actors, on which you need to repeat the first step to access the Recipe Executer.

		Doc:	VLT-MAN-ESO-19500-XXXX
ESO	Reflex FLAMES-UVES Tutorial	Issue:	Issue 1.10
LOU		Date:	Date 2018-04-01
		Page:	19 of 30

6.2.3 Recipe Execution within Composite Actors

The FLAMES-UVES workflow contains Composite Actors to run pipeline recipes. This is in the most simple case due to the SoF Splitter/SoF Accumulator⁵, which allow to process calibration data from different setting within one given DataSet (e.g. lamp frames taken with different preoptics/band-filters). More complex Composite Actors contain several actors (e.g. Recipe Executer).

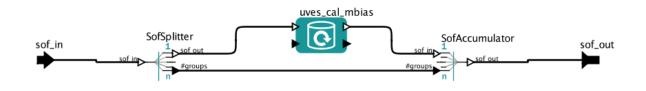


Figure 6.1: This is the window you get when you choose Open Actor for the Composite Actor Master Bias Creation. This is the most simple case for a Composite Actor. Using Configure Actor on uves_cal_bias_1 gives you Fig. 6.2.

The central elements of any Reflex workflow are the RecipeExecuter actors that actually run the recipes. One basic way to embed a RecipeExecuter in a workflow is shown in Fig 6.1, which is the most simple version of a Composite Actor. The RecipeExecuter is preceded by an SofSplitter, and followed by an SofAccumulator. The function of the SofSplitter is to investigate the incoming SoFs, sort them by "purpose", and create separate SoFs for each purpose. The RecipeExecuter then processes each of the SoFs independently (unless they are actually the same files). Finally, the SofAccumulator packs all the results into a single output SoF. The direct relation between the SofSplitter. A workflow will only work as intended if the purpose of all the files a recipe needs as input is identical. The only exception to this rule is that a purpose can also be "default". In this case, the file is included in any output SoF created by the SoFsplitter and SofAccumulator.

The reason for this scheme is best explained by an example. For a complex DataSet, the Data Organiser might have selected a large number of individual raw biases. The different biases are to be used to calibrate different frames, e.g. the science frames and the standard star frames. The Data Organiser determines and records this "purpose" of each bias, and this information is included in the DataSet and each SoF created from this DataSet. The FitsRouter directs all raw biases to the calibration Composite Actor. The SofSplitter then creates SoFs, one for the biases to be used for the science frames, and (probably) separate ones for the biases to be used for the science as a SoF that contains all the products.

A RecipeExecuter actor is used in the workflow to run a single FLAMES-UVES pipeline recipe (e.g. in the Master Bias Creation actor the recipe uves_cal_mbias is executed). In order to configure the RecipeExecuters, one has to first use Open Actor to get to the level of the recipe executors (see Fig. 6.1).

⁵SoF stands for Set of Files, which is an ASCII file containing the name (and path) of each input file and its category (e.g. BIAS).

Doc:	VLT-MAN-ESO-19500-XXXX
Issue:	Issue 1.10
Date:	Date 2018-04-01
Page:	20 of 30

recipe:	uves_cal_mbias	
mode:	Run	
Lazy Mode:		
Recipe Failure Mode:	\$RecipeFailureMode	
Input Files Category:		
Output Files Category:		
File Purpose Processing:	Strip last	
Allow empty inputs:		
Pause before execution:		
Pause after execution:		
Clear Products Dir:	Never	
Clear Logs Dir:	Never	
Clear Bookkeeping Dir:	Never	
Products Dir:	\$TMP_PRODUCTS_DIR	Brows
Logs Dir:	\$LOGS_DIR	Brows
Bookkeeping Dir:	\$BOOKKEEPING_DIR	Brows
EsoRex default args:	\$ESORexArgs	
recipe_param_1:	debug=false	
recipe_param_2:	plotter=no	
recipe_param_3:	process_chip=both	
recipe_param_4:	clean_traps=true	
recipe_param_5:	stack_method=median	
recipe_param_6:	klow=5	
recipe_param_7:	khigh=5	
recipe_param_8:	niter=5	
Reuse Inputs (Expert Mode):		
Reuse Outputs (Expert Mode):		
Commit Add	Remove Restore Defaults Preferences Help	Cancel

Figure 6.2: The "Edit parameters" window for a typical RecipeExecuter actor, the uves_cal_mbias actor which runs the uves_cal_mbias pipeline recipe.

In Figure 6.2 we show the "Edit parameters" window for a typical RecipeExecuter actor, which can be displayed by right-clicking on the actor and selecting Configure Actor. In the following we describe in more detail the function of some of the parameters for a RecipeExecuter actor:

- The "recipe" parameter states the FLAMES-UVES pipeline recipe which will be executed.
- The "mode" parameter has a pull-down menu allowing the user to specify the execution mode of the actor. The available options are:
 - Run: The pipeline recipe will be executed, possibly in Lazy mode (see Section 6.2.4). This option is the default option.
 - Skip: The pipeline recipe is not executed, and the actor inputs are passed to the actor outputs.
 - Disabled: The pipeline recipe is not executed, and the actor inputs are not passed to the actor outputs.
- The "Lazy Mode" parameter has a tick-box (selected by default) which indicates whether the RecipeExecuter actor will run in Lazy mode or not. A full description of Lazy mode is provided in Sect. 6.2.4.

Doc:	VLT-MAN-ESO-19500-XXXX
Issue:	Issue 1.10
Date:	Date 2018-04-01
Page:	21 of 30

actor	recipe	description
Master Bias Creation	uves_cal_mbias	create master bias
Calib Fibre Spectrum Locator	flames_cal_predict	create fibre line and order guess tables
calib Fibre Order Detection	flames_cal_orderpos	determine fiber order trace
Master Flat Creator	flames_cal_mkmaster	create master flat
Order Fibre Detection	flames_cal_prep_sff_ofpos	determine all fibre order traces
Wavelength Calibration Spectrum Extraction	flames_cal_wavecal flames_obs_scired	determines wavelength solution reduces science data

- The "Recipe Failure Mode" parameter has a pull-down menu allowing the user to specify the behaviour of the actor if the pipeline recipe fails. The available options are:
 - Stop: The actor issues an error message and the workflow stops.
 - Continue: The actor creates an empty output and the workflow continues.
 - Ask: The actor displays a pop-up window and asks the user whether he/she wants to continue or stop the workflow. This option is the default option.
- The set of parameters which start with "recipe param" and end with a number or a string correspond to the parameters of the relevant FLAMES-UVES pipeline recipe. By default in the RecipeExecuter actor, the pipeline recipe parameters are set to their pipeline default values. If you need to change the default parameter value for any pipeline recipe, then this is where you should edit the value. For more information on the FLAMES-UVES pipeline recipe parameters, the user should refer to the FLAMES-UVES pipeline user manual (Modigliani et al. 2013⁶).

The description of the remainder of the RecipeExecuter actor parameters are outside the scope of this tutorial, and the interested user is referred to the Reflex User Manual for further details (Forchì 2012). Any changes that you make in the "Edit parameters" window must be saved in the workflow by clicking the Commit button when you have finished to take effect. If you want to reuse the parameters you have to save the workflow with the saved parameters.

6.2.4 Lazy Mode

By default, all recipe executer actors in a pipeline workflow are "Lazy Mode" enabled. This means that when the workflow attempts to execute such an actor, the actor will check whether the relevant pipeline recipe has already been executed with the same input files and with the same recipe parameters. If this is the case, then the actor will not execute the pipeline recipe, and instead it will simply broadcast the previously generated products to the output port. The purpose of the Lazy Mode is therefore to minimise any reprocessing of data by avoiding data re-reduction where it is not necessary.

⁶Available at ftp://ftp.eso.org/pub/dfs/pipelines/uves/flames-uves-pipeline-manual-18.10.pdf

Doc:	VLT-MAN-ESO-19500-XXXX
Issue:	Issue 1.10
Date:	Date 2018-04-01
Page:	22 of 30

One should note that the actor's Lazy Mode depends on the contents of the directory specified by the parameter BOOKKEEPING_DIR and the relevant FITS file checksums. Any modification to the directory contents and/or the file checksums will cause the corresponding actor to run the pipeline recipe again when executed, thereby re-reducing the input data.

The re-reduction of data at each execution may sometimes be desirable. To force a re-reduction of data for any single RecipeExecuter actor in the workflow, right-click the actor, select Configure Actor, and uncheck the Lazy mode parameter tick-box in the "Edit parameters" window that is displayed. For many workflows the RecipeExecuter actors are actually found inside the composite actors in the top level workflow. To access such embedded RecipeExecuter actors you will first need to open the sub-workflow by rightclicking on the composite actor and then selecting Open Actor.

To force the re-reduction of all data in a workflow (i.e. to disable Lazy mode for the whole workflow), you must uncheck the Lazy mode for every single RecipeExecuter actor in the entire workflow. It is also possible to change the name of the bookkeeping directory, instead of modifying any of the Lazy mode parameters. This will also force a re-reduction of the given dataset(s). A new reduction will start (with the lazy mode still enabled), but the results of previous reduction will not be reused. Alternatively, if there is no need to keep any of the previously reduced data, one can simply set the EraseDirs parameter under the "Global Parameters" area of the workflow canvas to true. This will then remove all previous results that are stored in the bookkeeping, temporary, and log directories before processing the input data. In effect, starting a new clean data reduction and re-processing every input dataset.

6.3 Workflow Steps

6.3.1 Step 1: Data Organisation And Selection

On clicking the button on the Reflex canvas, the workflow will highlight and execute the Initialise actor, which among other things will clear any previous reductions if required by the user (see Section 6.1).

1. The DataOrganiser (DO) is the first crucial component of a Reflex workflow. The DO takes as input RAWDATA_DIR and CALIB_DATA_DIR and it detects, classifies, and organises the files in these directories and any subdirectories. The output of the DO is a list of "DataSets". A DataSet is a special Set of Files (SoF). A DataSet contains one or several science (or calibration) files that should be processed together, and all files needed to process these data. This includes any calibration files, and in turn files that are needed to process these calibrations. Note that different DataSets might overlap, i.e. some files might be included in more than one DataSet.

A DataSet lists three different pieces of information for each of its files, namely 1) the file name (including the path), 2) the file category, and 3) a string that is called the "purpose" of the file. The DO uses OCA⁷ rules to find the files to include in a DataSet, as well as their categories and purposes. The file category identifies different types of files. A category could for example be BIAS_RED,

⁷OCA stands for OrganisationClassificationAssociation and refers to rules, which allow to classify the raw data according to the contents of the header keywords, organise them in appropriate groups for processing, and associate the required calibration data for processing. They can be found in the directory <install_dir>/share/esopipes/<pipeline-version>/reflex/, carrying the extension.oca

WAVE_MOS_RED or SCIENCE_MOS_RED. The purpose of a file identifies the reason why a file is included in a DataSet. The syntax is action_1/action_2/action_3/ ... action_n, where each action_i describes an intended processing step for this file. The actions are defined in the OCA rules and contain the recipe together with all file categories required to execute it (and predicted products in case of calibration data). For example, a workflow might include two actions BIAS_RED and WAVE_MOS_RED. The former creates a master bias from raw bias frames, and the later creates (among other products) a wavelength calibration solution frame. The WAVE_MOS_RED action needs raw arc lamp frames and the master bias as input. In this case, these biases will have the purpose ACTION_BIAS_RED/ACTION_WAVE_MOS_RED. The same DataSet might also include biases with a different purpose, e.g. ACTION_BIAS_RED/ACTION_SCIENCE_MOS_RED. Irrespective of their purpose the file category for all these biases will be BIASES.

2. Next the DataSet Chooser displays the DataSets available in the "Select Data Sets" window⁸, activating a vertical scroll bar on the right if necessary (see Figure 4.3). Sometimes you will want to reduce a subset of these DataSets rather than all DataSets, and for this you may individually select (or de-select) DataSets for processing using the tick boxes in the first column, and the buttons Select All and Deselect All at the bottom left.

You may also highlight a single DataSet in blue by clicking on the relevant line. If you subsequently click on Inspect Highlighted, then a "Select Frames" window will appear that lists the set of files that make up the highlighted DataSet including the full filename and path for each file, the file category (from the FITS header), and a selection tick box in the right column (see Figure 6.3). The tick boxes allow you to edit the set of files in the DataSet which is useful if it is known that a certain calibration frame is of poor quality (e.g: a poor raw flat-field frame). The list of files in the DataSet may also be saved to disk as an ASCII file by clicking on Save As and using the file browser that appears.

By clicking on the line corresponding to a particular file in the "Select Frames" window, the file will be highlighted in blue, and the file FITS header will be displayed in the text box on the right (see Figure 6.3), allowing a quick inspection of useful header keywords. If you then click on <code>Inspect</code>, the workflow will open the file in the selected FITS viewer application defined by the workflow parameter <code>FITS_VIEWER</code>.

To exit from the "Select Frames" window, click <u>Continue</u>, and to exit from the "Select DataSets" window, click either <u>Continue</u> in order to continue with the workflow reduction, or <u>Stop</u> in order to stop the workflow.

The categories and purposes of raw files are set by the DO, whereas the categories and purpose of products generated by recipes are set by the RecipeExecuter (see Sect. 6.2.3). The file categories are used by the FitsRouter to send files to particular processing steps or branches of the workflow (see below). The purpose is used by the SofSplitter to generate input SoFs for the RecipeExecuter and the results are collected by the SofAccumulator. Note that while the DO includes files into a DataSet for a reason, and records this reason as the "purpose" of the file, the workflow itself can use these files in a different manner. The SofSplitter and SofAccumulator accept several SoFs as simultaneous input. The SofAccumulator creates a single output SoF from the inputs, whereas the SofSplitter creates a separate output SoF for each purpose.

⁸If you run the Data Organiser in Lazy Mode, changes in the Keywords to be displayed list will have no effect on the output shown in the DataSet Chooser.

		Doc:	VLT-MAN-ESO-19500-XXXX
ESO	Reflex FLAMES-UVES Tutorial	Issue:	Issue 1.10
LOU		Date:	Date 2018-04-01
		Page:	24 of 30

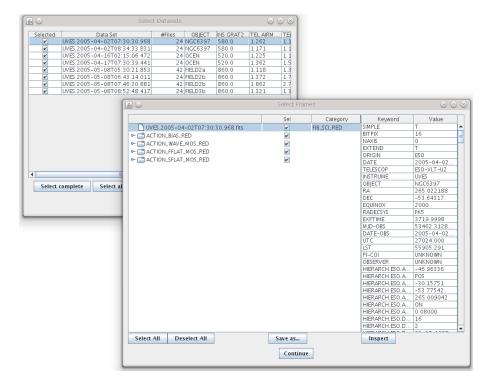


Figure 6.3: The "Select Frames" window with a single file from the current Data Set highlighted in blue, and the corresponding FITS header displayed in the text box on the right. Hidden partially behind the "Select Frames" window is the "Select DataSets" window with the currently selected DataSet highlighted in blue.

Doc:	VLT-MAN-ESO-19500-XXXX
Issue:	Issue 1.10
Date:	Date 2018-04-01
Page:	25 of 30

6.3.2 Step 2: Recipe execution

Once the datasets to be reduced are selected, press the Continue button on the dataset organised window to proceed with the data reduction. The workflow will automatically execute the pipeline recipes and construct the .sof files to feed the pipeline recipes with. Each sof file will be saved in the BOOKKEPING_DIR directory (and subdirectory within it), depending on the recipe it is associated to and the execution time. The pipeline parameters can be changed as shown in figure 6.2.

6.3.3 Step 3: Final products

Once a dataset is reduced (i.e. when the flames_obs_scired recipe is terminated), a window containing the list of science product pops up. Each file can be inspected with the selected fits viewer. Final science products will be stored in the END_PRODUCTS_DIR, and sorted by execution time and dataset identifier (i.e. the name of the science frame the dataset is for). Default names for the science products are: <TARG name>_ERR_MWXB_SCI_<CHIP>.fits, <TARG name>_FIB_SCI_INFO_TAB_<CHIP>.fits, <TARG name>_MWXB_SCI_<CHIP>.fits (where <CHIP> may be REDL or REDU). We refer the user to the FLAMES-UVES pipeline manual for the description of these files.

7 Troubleshooting

In this section we describe some of the problems that may occur when reducing the FLAMES-UVES with the ESOrex pipeline. For a more comprehensive description we refer the user to the FLAMES-UVES user manual (http://www.eso.org/sci/software/pipelines/).

1. Should I change the CALIB_DATA_DIR configuration?

This directory is setup automatically to point to the calibration database provided with the pipeline and in principle shouldn't be changed. However, if static calibration data are present in the RAWDATA_DIR (e.g. calibrations are downloaded from the archive, or copied from ESO-DVD distribution), then you might have to set this directory equal to RAWDATA_DIR (otherwise an obsolete static calibration file may be selected instead of the most appropriate one).

- 2. Spectrum extraction failing with error "Keyword ESO TEL GEOLAT does not exist" From time to time the reduction of science frames may fail indicating that "Keyword ESO TEL GEOLAT does not exist". This keyword is required to measure heliocentric velocity correction. The user should make sure the input data have proper FITS header, in particular contains the keywords "RA", "DEC", "ESO TEL GEOLAT", "ESO TEL GEOLAT", "UTC", "MJD-OBS".
- 3. Spectrum extraction failing with error "Input data do not match: Spectrum contains 12 orders, but line table absolute order numbering is 70 60" while reduction 860 setting data. This problem is due to the fact that the wavelength calibration has switched off the generation of a solution for some fibre beacuse has not found the minimum number of searched liunes (minimum set to 1000). In this case we recommend the user to set the parameter minlines of flames_cal_wavecal to 600 (or less), and repeat the flames_cal_wavecal and flames_obs_scired steps.
- 4. Not good spectrum extraction quality We are aware that the science reduction on platforms where the compiler is clang (for example MacOSX) may be not good. We recommend the user to install and compile the kit using the GNU compiler (gcc).

Doc:	VLT-MAN-ESO-19500-XXXX
Issue:	Issue 1.10
Date:	Date 2018-04-01
Page:	27 of 30

8 Frequently Asked Questions

• The error window fills the whole screen - how can I get to the Continue / Stop buttons?

Press the Alt key together with your left mouse button to move the window upwards and to the left. At the bottom the Continue Stop buttons will be visible. This bug is known but could not yet be fixed.

• I tried to Open (or Configure) an Actor while the workflow is running and now it does not react any more. What should I do?

This is a limitation of the underlying Kepler engine. The only way out is to kill the workflow externally. If you want to change anything while a workflow is running you first need to pause it.

• After a successful reduction of a data set, I changed this data set in some way (e.g. modified or removed some files, or changed the rules of the Data Organizer). When I restart Reflex, the Data Set Chooser correctly displays my new data set, but marks it as "reduced ok", even though it was never reduced before. What does this mean?

The labels in the column "Reduced" of the Data Set Chooser mark each dataset with "OK", "Failed" or "-". These labels indicate whether a data set has previously successfully been reduced at least once, all previous reductions failed, or a reduction has never been tried respectively. Data sets are identified by their name, which is derived from the first science file within the data set. As long as the data set name is preserved (i.e. the first science file in a data set has not changed), the Data Organizer will consider it to be the same data set. The Data Organizer recognizes any previous reductions of data sets it considers to be the same as the current one, and labels the current data set with "OK" if any of them was successful, even if the previously reduced data set differs from the current one.

Note that the Product Explorer will list all the previous reductions of a particular data set only at the end of the reduction. This list might include successful and/or unsuccessful reduction runs with different parameters, or in your case with different input files. The important fact is that these are all reductions of data sets with the same first raw science file. By browsing through all reductions of a particular raw science file, the users can choose the one they want to use.

- Where are my intermediate pipeline products? Intermediate pipeline products are stored in the directory <TMP_PRODUCTS_DIR> (defined on the workflow canvas, under Setup Directories) and organised further in directories by pipeline recipe.
- Can I use different sets of bias frames to calibrate my flat frames and science data? Yes. In fact this is what is currently implemented in the workflow(s). Each file in a DataSet has a purpose attached to it (Forchì (2012)). It is this purpose that is used by the workflow to send the correct set of bias frames to the recipes for flat frame combination and science frame reduction, which may or may not be the same set of bias frames in each case.
- $\bullet\ Can \ I \ run \ {\tt Reflex}$ from the command line? Yes, use the command:

esoreflex -n <workflow_path>/<workflow>.xml

The -n option will set all the different options for Kepler and the workflows to avoid opening any GUI elements (including pipeline interactive windows).

It is possible to specify workflow variables (those that appear in the workflow canvas) in the command line. For instance, the raw data directory can be set with this command:

esoreflex -n -RAW_DATA_DIR <raw_data_path> \ <workflow_path>/<workflow>.xml

You can see all the command line options with the command esoreflex -h.

Note that this mode is not fully supported, and the user should be aware that the path to the workflow must be absolute and even if no GUI elements are shown, it still requires a connection to the window manager.

- How can I add new actors to an existing workflow? You can drag and drop the actors in the menu on the left of the Reflex canvas. Under Eso-reflex -> Workflow you may find all the actors relevant for pipeline workflows, with the exception of the recipe executer. This actor must be manually instantiated using Tools -> Instantiate Component. Fill in the "Class name" field with org.eso.RecipeExecuter and in the pop-up window choose the required recipe from the pulldown menu. To connect the ports of the actor, click on the source port, holding down the left mouse button, and release the mouse button over the destination port. Please consult the Reflex User Manual (Forchì (2012)) for more information.
- How can I broadcast a result to different subsequent actors? If the output port is a multi-port (filled in white), then you may have several relations from the port. However, if the port is a single port (filled in black), then you may use the black diamond from the toolbar. Make a relation from the output port to the diamond. Then make relations from the input ports to the diamond. Please note that you cannot click to start a relation from the diamond itself. Please consult the Reflex User Manual (Forchì (2012)) for more information.
- How can I manually run the recipes executed by Reflex? If a user wants to re-run a recipe on the command line he/she has to go to the appropriate reflex_book_keeping directory, which is generally reflex_book_keeping/<workflow>/<recipe_name>_<number> There, subdirectories exist with the time stamp of the recipe execution (e.g. 2013-01-25T12:33:53.926/). If the user wants to re-execute the most recent processing he/she should go to the latest directory and then execute the script cmdline.sh. Alternatively, to use a customized esorex command the user can execute

```
ESOREX_CONFIG="INSTALL_DIR/etc/esorex.rc"
PATH_TO/esorex --recipe-config=<recipe>.rc <recipe> data.sof
```

where INSTALL_DIR is the directory where Reflex and the pipelines were installed.

If a user wants to re-execute on the command line a recipe that used a specific raw frame, the way to find the proper data.sof in the bookkeeping directory is via grep <raw_file> */data.sof. Afterwards the procedure is the same as before.

If a recipe is re-executed with the command explained above, the products will appear in the directory from which the recipe is called, and not in the reflex_tmp_products or reflex_end_products directory, and they will not be renamed. This does not happen if you use the cmdline.sh script.

• If I enter "-" into an empty integer parameter of an interactive window it is automatically completed to "-1". Why?

The parameters are validated for correctness according to their type (e.g. string, integer, float). In the case of an integer or float parameter "-" alone is considered an invalid input and is therefore automatically completed to "-1". This is part of the validation of input done by the WxPython library.

• Can I reuse the bookkeeping directory created by previous versions of the pipeline?

In general no. In principle, it could be reused if no major changes were made to the pipeline. However there are situations in which a previously created bookkeeping directory will cause problems due to pipeline versions incompatibility. This is especially true if the parameters of the pipeline recipes have changed. In that case, please remove the bookkeeping directory completely. Forchì V., 2012, Reflex User Manual, VLT-MAN-ESO-19000-5037, Issue 0.7, *ftp://ftp.eso.org/pub/dfs/reflex/ReflexUserManual-3.1.pdf* 17, 21, 27, 28

FLAMES-UVES Pipeline User Manual, VLT-MAN-ESO-19500-3016, Issue 18.1021